#### **ELECTRONICS AND DEFENSE**



## **FMU-500**

# FIBER OPTIC MEASUREMENT UNIT

The Inertial Measurement Unit "FMU-500" is a general-purpose sensing unit, providing digital measurement data of angular rates and linear accelerations relative to three orthogonal body fixed axes.

The FMU is based on a 3-axis Fiber Optic Gyro configuration. The accelerometers are selectable as closed loop silicon micropendulum sensors or quartz VBA sensors. This IMU has been specifically designed for civil & industrial applications which need high reliability, excellent signal stability, and very low noise.

#### **KEY FEATURES AND BENEFITS**

Civilian product export classification/ITAR free

Unlimited bandwidth, white noise = well suited for high speed, high performance stabilization

Adjustable form factor = simple to integrate into customer architecture = ideally suited for stabilization of geo-referenced systems

Closed-loop stable and low-noise FOG gyroscope characteristics

Magnetic shielding, advanced mechanical design for sensor de-coupling

Available in 3 confi gurations; "open-frame", "light-packaging" and "hermetic packaging"

#### PERFORMANCE SPECIFICATIONS

Measurement range:	≥ 300 °/s
Bias (over the temperature range):	0.07 °/h (typ.)
	≤ 0.5 °/h (max)
In-run stability :	0.05 °/h <i>(typ.)</i> ≤ 0.1 °/h (max)
Scale-factor accuracy (over temp rang	ge): 50 ppm (typ.)
Scale-factor non linearity :	< 100 ppm
Noise:	$< 0.85^{\circ}/h/\sqrt{Hz}$
Angle random walk :	$0.009^{\circ}/\sqrt{hour}$ (typ.)
Bandwidth :	up to 1000 Hz
RS-422 synchronous	
Baud rate :	2 Mbit/s
Data rate : 200 Hz	(nominal), ≥ 2000 Hz (max)

### Featured Applications

Helicopter Autopilots
Hybrid Navigation & Geo-Localization
High-Performance Stabilization
Attitude & Heading Reference Systems
Automatic Flight Control Systems

Redundant IMU for HRG, RLG, or MEMS Gyro based Unmanned Navigation Systems Pipeline, Geodesy & Aerial Surveys Industrial Robotics

## **DATASHEET FOR FMU-500**

ELECTRICAL / MECHANICAL	
Initialization Time (valid data)	≤ 100 ms (first transmission of data)
Data Interface Synchronous	TYPE RS-422
Baud Rate	2 Mbit/s
Data Rate	200 Hz (nominal), ≥ 2000 Hz (max)
Dimensions (max)	93 x 93 x 114 mm (w/o connector)
Weight (unpackaged)	≤ 1400 g
Power Consumption	8 - 12 W (typical), 19 W (max)
Input Voltage	±15 VDC, +5 VDC

ENVIRONMENT	
Temperature (operating, performance)	-45°C to +85°C / -40°C to +71°C (Ground survival is -55°C to +85°C)
Shock (operating)	6 g, 11ms
Vibration (operating / survival)	10 2000 Hz, 1 grms random 20 2000 Hz, 6.3 grms random

ACCELEROMETERS (Quarz VBA)		
Input Limit (max)	± 13g ± 10%	
Bias Instability (const. Temp)	0.003 mg (typ.)	
Scale Factor Temperature Sensitvity	≤ 200 ppm rms	
VRW (25°C)	0.9 μm/s/ $\sqrt{Hz}$	
Bandwidth (-3 dB)	≥ 500 Hz	

ALL ERRORS ARE DEFINED AS  $1\sigma$ -VALUES IF NOT STATED OTHERWISE

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